

# UAV SAFETY REQUIREMENTS

## UAV CATASTROPHIC EVENT

UAV LOSS  
combined with  
HITTING PEOPLE

COURSE DEVIATION  
COMBINED WITH  
COLLISION WITH  
ANOTHER A/C

$$\begin{aligned}
 P_{catastrophic} &= P_{UAV \text{ System Loss}} \times P_{Hitting \text{ People}} = \\
 &= P_{UAV \text{ System Loss}} \times \left( DP_{\text{Density Population}} \times A_{debris} \right)
 \end{aligned}$$

### MINIMUM EQUIPMENTS/SYSTEMS:

- navigation and anti-collision lights (24 hours a day)
- Communication System "Earth/Board/Earth"
- a telephone inside the Ground Control Station
- Transponder

### INVESTIGATE THE FEASIBILITY TO ADAPT AND USE SYSTEMS AS:

- Traffic Collision Avoidance System (TCAS),
- Low Altitude Alerting System,
- Ground Proximity Warning System (GPWS),
- Terrain Awareness and Warning System (TAWS),
- Automatic Dependent Surveillance - Broadcast (ADS-B)

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ARMAEREO

P (SYSTEM LOSS)

SSA

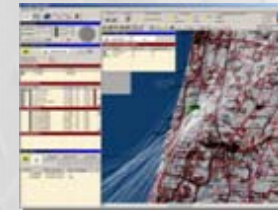


P (HITTING  
PEOPLE ON  
GROUND)

A/C INHERENT RELIABILITY



POPULATION DENSITY



THE INTRODUCTION OF THE **POPULATION DENSITY** ALLOWS TO CERTIFY THE DESIGN OF UAV SYSTEM WITH LOW INHERENT RELIABILITY (RATE OF SYSTEM LOSS), THOUGH MAINTAINING AN HIGH DEGREE OF **SAFETY AGAINST THIRD PARTIES**